

Datasheet

Lodestar 200 Subsea AHRS



Description

Lodestar 200 is a combined solid state Attitude and Heading Reference System (AHRS), which is upgradable to SPRINT Acoustically Aided Inertial Navigation System [AAINS].

The unit is comprised of three high grade, high reliability, commercially available, Ring Laser Gyros (RLG) and accelerometers. The sensors are also the standard for commercial aviation with a proven 15+ year track record.

Lodestar 200 AHRS provides heading, pitch, roll accuracy and settle time that is class leading in the low-cost north seeking subsea AHRS category. It requires no external aiding and can settle in <15 minutes or less in dynamic conditions.

On-board data storage and backup battery functionality ensures continued operation and no data-loss even if communications or external power is lost.

Lodestar 200 AHRS is designed for subsea vehicle integration and provides industry standard gyrocompass for simple interfacing.

In addition, advanced outputs such as acceleration and rotation rates are also provided to support ROV autopilot and station keeping functions.

Lodestar 200 AHRS has built-in field upgradability to the higher performance Lodestar 300 AHRS and SPRINT 300 aided INS. This feature allows operators to equip their vehicles with a cost effective AHRS at vehicle assembly whilst ensuring commercial and operational flexibility to upgrade as and when needed in the field.

The optional SPRINT upgrade provides a dual algorithm capability, which is unique in the market and allows for dual use from one inertial instrument, e.g. Lodestar AHRS for ROV, SPRINT INS for Survey teams.

Lodestar and SPRINT have a proven track record spanning 10 years.

The instrument is available in 4,000 and 6,000 metre depth ratings and is one of the smallest form factor subsea inertial instruments available.

Applications Include

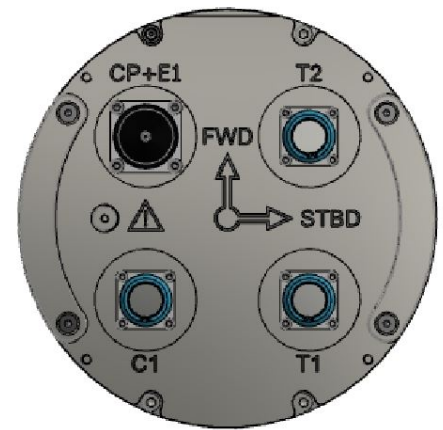
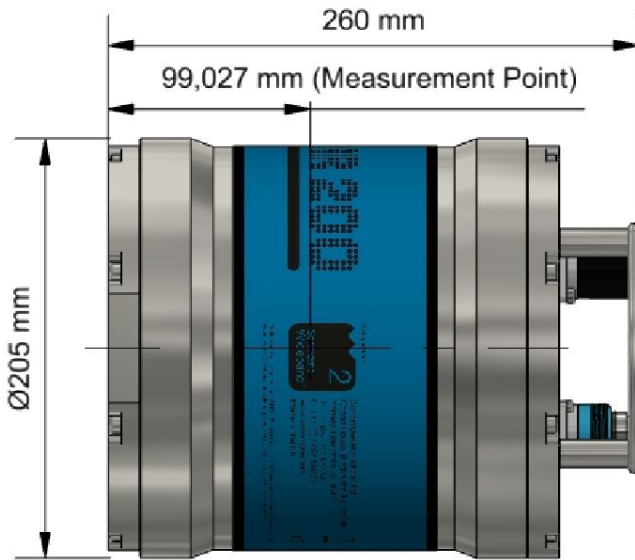
- ROV gyrocompass
- Vehicle guidance

Key Features

- Single box solution for motion sensor and gyrocompass
- 0.4 secant latitude heading accuracy
- 0.01° roll and pitch accuracy
- <10 minute settling time
- Fast follow up speed of 900°/sec**
- MTBF inertial sensors (RLG and Accelerometer) > 400,000 hours
- Choice of depth ratings: 4,000 and 6,000 metres
- Choice of connectors: Seacon (standard) or Seaneat® (for use with FMC Schilling Robotics ROV)
- Transport approved rechargeable Li-ion battery back-up as standard
- Minimum internal memory of 8 GB allows post processing and remote diagnostics
- Ethernet interface
- Lodestar 200 AHRS can be remotely upgraded to Lodestar 300 AHRS or SPRINT 300 INS

Specifications

Lodestar 200 Subsea AHRS



| Feature | Lodestar | Type 8084-xxx | Type 8084-xxx | Type 8084-xxx |
|---------------|---|--|----------------------|---------------|
| Depth Rating | | 4,000 metres | 4,000 metres | 6,000 metres |
| Physical | Size (Diameter x Length) | Ø205 x 260 mm | Ø205 x 250 mm | Ø205 x 280 mm |
| | Weight in Air/Water* | 18.5/11.5 kg | 18.5/11.5 kg | 22/14 kg |
| | Mechanical Construction | Titanium | Titanium | Titanium |
| | Connectors | 1 x Seacon | 1 x Seacon® | 1 x Seacon |
| | Performance | Heading Accuracy | 0.4° (Lodestar AHRS) | |
| | Roll and Pitch Accuracy | 0.01° | | |
| | Settle Time | <10 minutes in dynamic conditions (AHRS) | | |
| Upgrades | Lodestar 200 AHRS can be remotely upgraded to Lodestar 300 AHRS or SPRINT 300 INS | | | |
| Environmental | Temperature | -20 to +55°C (operating), -20 to +60°C (storage) | | |
| | Shock Rating | 22 g, 11 ms half sine | | |
| Power | Power Requirement | 24/48 V DC, 15 W nominal, 35 W max | | |
| | Back Up Battery Type/Life | Li-ion/5 minutes | | |
| | Data/Comms. | Data Storage | 8 GB internal memory | |
| | Digital Ports/Protocol | 1 digital Port/RS232 or RS485 | | |
| | Other Ports | 1 x Ethernet, 1 Triggers | | |
| | Output Rate | Up to 100 Hz | | |
| | Output Telegrams | Industry standard AHRS/INS telegrams including acceleration and rotation rates** | | |

*Estimated Weights

**Specific outputs such as acceleration and rotation rates may be limited below quoted performance for reasons of export classification and control